

APPLICATION NOTE: DAC Analog I/O Applications

APN-1001

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SUMMARY

This applications note focuses on DAC Analog Input/Output applications, but also includes basic setup and connection information on the Titan System. This document is not intended to replace the Titan Control System (TCS) or Titan Hardware User Manuals. Please consult these manuals for additional specific information.

TITAN SYSTEM OVERVIEW

A Titan System may consist of up to eight Pods or Mini-Recorders, and a CPU. The System may also include one or more DACs and/or Digital Pods as shown:



TEST CONFIGURATIONS WITH DACS

The Titan system allows great flexibility in setting up various test configurations. Using a simplified Titan system of just a few Pods and DACs to serve as examples, some common system configurations are shown below.

Configuration 1 – Two Pod/DAC pairs into a Titan CPU



Configuration 1 shows each Pod/DAC pair powered from a single power adapter. Short lengths of CAT 5 cable connect the Pods to the DACs. Longer lengths of CAT5 cable connect the DACs to CPU ports 1 and 2; this configuration allows the CPU to be located some distance away. An Ethernet connection on the CPU provides network connectivity for remote data acquisition.



Configuration 2 – One Pod/DAC pair into a Titan CPU, one Pod/DAC pair into a PC running TCS

Configuration 2 shows each Pod/DAC pair powered from a single power adapter. As with the first configuration, short lengths of CAT 5 cable connect the Pods to the DACs. A long length of CAT5 cable connects the first DAC to the CPU. Another length of CAT5 cable connects second DAC to an RS422-to-USB converter, and a USB cable connects to the PC.

Configuration 3 – One Pod/DAC pair into a PC running TCS



Configuration 3 shows the Pod/DAC pair powered from a single power adapter. A short length of CAT 5 cable connects the Pod to the DAC, and a USB cable connects the DAC to the PC. For this configuration, the PC must be located reasonably close to the DAC (within the 15 ft distance limit of USB).

CABLES & CONNECTIONS

Data connections in the Titan System are made using standard CAT5 Ethernet 'straight-through' cable for connections between the Pod and DAC, and between the DAC and CPU. Connections are made according to the configuration diagrams 1 & 2 as shown above. The maximum recommended Ethernet cable length between devices is 100 feet.

Standard USB cable is used for data connections between a single Pod or Pod/DAC pair and a PC, as shown in configuration 3 above.

RECOMMENDED POWER-UP SEQUENCE

After all connections have been made, the recommended startup sequence is as follows:

- 1. Apply power to the Pod/DAC pair and wait for them to initialize
- 2. Apply power to the CPU

Note: When the CPU powers-up, it automatically performs a check to detect all connected devices as a part of its initialization sequence. If a Pod is not powered and active during this time, it will not be detected. In this case, you will need to perform a manual query by clicking on the 'ReQuery Devices' button in TCS. The Titan CPU will then rescan the ports. All connected Titan devices should be detected and appear in the device list in TCS.

CONFIGURING TCS

After system connections are made, the next step is configuring TCS. This is a four-step process:

- 1. Create or Load a Test
- 2. Configure the Titan Device
- 3. Configure the Sensors
- 4. Assign Sensors to Channels

Note: If TCS has not been installed on the PC that will be used, follow the installation instructions in the TCS User Manual.

1. Create or Load a Test

Launch TCS. In the start-up screen you will be prompted either to create a new test or load an existing test. When you create a new test, you must specify the Device Type (explained below). When you load an existing test, the Device Type is already specified.

a. Create a Test

For new tests, TCS defaults to assigning a test name based on the selected device type and the current date. There are three devices types to choose from:

Mini-Recorder: Choose this type when using a single Titan Mini-Recorder or Titan Pod CPU: Choose this type when using a Titan CPU with 2 or more Mini-Recorders/Pods with or Without DACs

DAC: Choose this type when using a Mini-Recorder or Pod with a DAC over a USB connection

Note: A Mini-Recorder is a Pod with built-in recording capability. For consistency, the term 'Pod' will be used throughout this document to refer to either device.

For new tests, you will need to select the desired device type in the start-up screen:

📕 Welcome to TITAN		-D×
Please Create	or Load a Test	
Create New Test		
Test Name	pod_4-30-2012]
Device Type	Mini-Recorder	
	O Titan CPU	
	O Mini-Recorder + DAC	
	Create	
Load Existing		
	Browse	

Note that new tests will always use a default name of the type <device type>_<date>. To change the name, click in the test field and enter an alternate test name, keeping in mind that test names cannot contain spaces. All data taken during this session will be exported using this test name. When finished, click 'Create'

b. Load a Test

To load an existing test, click on the 'Browse' button and navigate to the location of the test (test files always have a .tcf extension).



After locating and selecting the desired test, clicking 'Open' (or simply double-clicking on the test file) will load the test into TCS.

Note: TCS includes a built-in help feature, available on any screen in TCS simply by pressing 'CTRL H'. You can also access Help through the HELP menu.

When help is activated, TCS launches the TCS User Manual and displays the information related to the current screen. Note that for the Help function to work, you must have the Adobe Reader application installed.

2. Configure the Connected Device

a. Titan Pod/DAC pair over USB

For test configurations where a DAC is used, the Device Settings in TCS should be set to 'Low Speed' with a Scan Rate of '1200 Hz'. These settings are automatically established when 'Mini-Recorder + DAC' is selected as the device type in TCS:

🔚 Welcome to TITA	1	- DX
Please Create	or Load a Test	
Create New Test		
Test Name	dad_4-30-2012	
Device Type	O Mini-Recorder	
	O Titan CPU	
	Mini-Recorder + DAC	
	Create	
Load Existing	Browse	

When 'DAC' is selected as the device type, TCS will launch with a Device Configuration screen that is configured for a single Pod/DAC pair, in Low Speed Mode with a 1200 Hz Scan Rate. For this configuration, TCS also adds a DAC Information field in the lower part of the window.

1:1	Configuration			2 Dunting				3 Expert	
A: Device Configuration			D.C	2. Humane			3 Export		
A Device Comp	aronom		B. Sensors			2 Tags and Unannets		D. Recording Uptions	
Name: DAC			Speed						
			Moder	Low Speed	~				
ect Port	Device Information		Sour Pater	1000		Standalone GPS	5		
ni-Recorder on COM461	Device Type	BMS16H-53	Scannae.	1200	×	Enable GPS	Enable PPS		
	Serial Number	1392-08	Filter Frequency:	200 Hz	~		Bypass Lock 🗹		
	Firmware Version	0.29.0	Excitation			Digital Pod			
	Cal Due Date	12/05/12	Excitation Value:	2.048	v	Enable	Digital Pod		
Query Serial Devices	- Recorder Information		Supports Per-0	hannel Excitat	ion 🗹		Configuration		
ud Rate:	SD size		Other Settings						
uto 🗸 🗌 Set	Free Space		Input Attenuator 0	lifset 2.184	~				
				_		Auto Record I			
						Add Hecord			
	DAC Information	Decision at							
	UAL Type	DAC1602-21							
	Fittiware Version	DAC_V1.7							

b. Titan CPU

🔜 Welcome to TITAN		_ D ×
Please Create	or Load a Test	
Create New Test		
Test Name	cpul_4-30-2012	
Device Type	O Mini-Recorder	
	⊙ Titan CPU	
	O Mini-Recorder + DAC	
	Create	
- Load Existing		
	Browse	

To create a test for a Titan CPU, select 'Titan CPU' as the device type:

For the CPU test, TCS will display a 'Device Configuration' screen like the one below.

Begin by selecting the network address of the connected Titan CPU device. The address is listed on a label on the top of the CPU hardware; this address should appear in the 'Select Port' field in TCS. If the address does not appear, click on 'Query for CPU'. After the 'Select Port' field updates, select the correct device address and then click 'Connect' (function key F1) to connect to the Titan CPU



" Mars Labs TCS 2.6.4 Current test: cpu_	11-22-2011						
Test Device Settings Help				Local Index:	: 0000 Free: 133.74 GB	Device Index: 0000	Free: 0 K
1: Configuration	2: Runtime				3.1	Export	
A: Device Configuration	B: Sensors	B: Sensors C: Tags and Ch		Channels	C	. Recording Options	
Name: [LPU Select Port ILP2(15)10(5) Remove IP Add IP Query for CPUs Need to 'Get Info' ReQuery Devices		Speed 1 Mode: Scan Rate: Filter Frequency:	High Speed W 200 W 99 Hz W		CPU Settings Auto Monit	Start Record or Mode	
F1 F2 F3 F4 Get Info	F5 Add Pod	F6 Remove Pod	F7 F8		F9 F10 Manual Command	F11 In-Vehicle Display	F12

Note: The 'CPU Settings' pane in the example above is used to set the power-up condition of the CPU. The three checkboxes function as follows:

Auto Start: When checked, this enables the Auto Start feature. 'Auto Start' commands all connected Titan hardware to begin scanning when the CPU powers up.

Auto Record: When checked, this enables the Auto Record feature. When enabled, the CPU will begin recording a dataset upon power-up.

Monitor Mode: When checked, Monitor Mode is enabled. Monitor Mode prevents the CPU from altering device configurations. When Monitor Mode is enabled, the CPU will not query devices and will not send any commands to connected devices. Instead, it will load the configuration it used for the previous run and assume it is connecting to the same devices already running.

After connections are established, the 'Device Information' fields will be filled with information about the connected Titan hardware, as shown below. To complete the Titan Device configuration, select the desired scan rate and the filter frequency of the Titan CPU from the drop-down menus. The speed, scan rate and filter frequency for the Titan CPU will be applied to all connected Titan devices.

W Mars Labs TCS 2.6.4.5 Current test: cpu_2	2-10-2012	Level teday, 200	
1: Configuration		Device index: 0000 mee: 00ytes	
A: Device Configuration	2: Hu B: Sensors	C: Tags and Channels	J. Recording Options
Name: [CPU Select Port: 1922-198-110-161 Device Information Device Type [1] Setial Number [14] Firmware Version [1] Query for CPUs	Speed 1 S S S S S Filter F	Mode: Low Speed w can Rate: 1200 w requency: 100 Hz w	CPU Settings
Pod (Port 1) Device Information Device 1 Device Device Type Detected 1 Device Description Re-Query Devices Cal Due Date	BMS16H-53 B Series 1392:08 023:0 12/05/12 ↓ Speed Excitat Excitat Excitat Secies Convert Excitat Excitat Secies Convert Excitat Secies Convert Excitat Secies Convert Secies Convert Secies Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Convert Secies Secies Convert Secies Convert Secies Convert Secies Secies Convert Secies Sec	Pot 1 peed, Scan Rate: 1200, Filer: 100 Hz ion ation Value: 2048 composite Per-Channel Excitation Settings ut Attenuator Offset 2184 MWFT	Standalone GPS Enable GPS Enable PPS / Bypass Lock / Digital Pod Enable Digital Pod Configuration
F1 F2 F3 F4 Get Info	F5 Add Pod Remove Pod	F7 F8	F9 F10 F11 F12 Manual Command Display

NOTES:

- 1. When a CPU configuration includes a DAC, you must select Low Speed mode with a 1200Hz scan rate.
- 2. If the Titan CPU is configured for High Speed operation when Low Speed Titan Pods or Mini-Recorders are connected, an error will result.
- 3. For complete information on all CPU Device Configuration screen options, see 'Advanced Settings' in the TCS User manual.

The Titan CPU supports up to 8 Titan Pods. Titan devices can be added or removed from the Titan CPU as needed, but any new devices are not automatically detected. If you wish to add additional Titan Pods after the initial configuration (the Titan CPU auto-detects devices only upon power-up), make the connections and then click on the 'Re-Query Devices' button. The Titan CPU will scan all ports for new devices, and TCS will display a status message during the process:

Please wait		- D X
	CPU is querying devices	
	This will take a little while.	

All connected Titan devices should be detected and appear in the device list in TCS.

3. Configure the Sensors

Configure the Sensors by clicking on the 'Sensors' tab. The Sensors screen allows you to enter and configure the various sensors that will be used in the test (Accelerometers, Strain Gauges, etc).

M Mars Labs TCS 2.6.4.5 Ci	urrent test: _AB7346				- D ×	
Test Device Settings Help			Local	Index: 0000 Free: 13	32.72 GB Device Index: 0000 Free: 0 KB	
1: Configuration		2: R	untime		3: Export	
A: Device Configuration		B: Sensors	C: Tags and Chann	nels	D. Recording Options	
Voltage Acceletation Acceletation Acceletation Digial Displacement Load Pressure	Name: Accel_218 scription g v Eng Units g v Type: Solid State v	Gravity C Sensitivity 48.5334 Sensitiv 1 9 1 /V Ex	Manufacturer Silicon De Model 2264-010 Serial Number 218 Cal Due Date 11/20/10 ustom Units Input Recitation Source Excitation Value	at Dividers Enabled	Shurit Calibration Shurit Value 100000 Gauge Resistance 350 Manual RCal - Target RCal - Target 0 Manual RCal + Target RCal + Target 0	
Name Units Manuf	facturer Model	Serial Sensitivity		Offset	^	
Accel_218 g Silicon	Designs inc 2264-010	218 48.5334 mv / 1 g				
F1 F2 F Connect Sen	F3 F4 port Export Sensors	F5 New Sensor Sensor	F7 F8 Physical Cal	F9 M Cor	F10 F11 F12 anual In-Vehicle Display Sensor Help	

To add a sensor, click on the 'New Sensor' button [F5]. In the new window, type in the desired name of the sensor. Select the sensor type from the 'Type' drop-down menu, and then click 'OK'. Note that once you click 'OK' the sensor name cannot be changed.

📰 Enter se	ensor name and type	
Name:	Accel_232	
Туре:	Acceleration	~
	Voltage Acceleration Strain Digital Thermocouple	
	Displacement Load	*

NOTE: You can also create a new sensor simply by double-clicking on the desired sensor type in the Sensor Tree. Any sensors created in this manner will be named automatically - you will not be able to specify the sensor name.

As sensors are added, each name will appear in the Sensor Tree on the left side of the window. You can enter additional information about each new sensor (description, manufacturer, model, etc.) in the editable fields. A table at the bottom of the window provides an overview of all of the sensors available in the test. Note that the table is for display only; it cannot be used for editing.

M Mars Labs TCS 2.6.4.5	Current test: Dytran_1	_20120210GEG				
Test Device Settings H	ielp			Local Index:	0000 Free:	217.84 GB Device Index: 0000 Free: 0 byt
1: Config	puration	2: Ru	intime			3: Export
A: Device Configurat	ion	Sensors	C: Tage	and Channels		D. Recording Options
Voltage Vo	Name: Accel_0189 Description Eng Units g v Type: Solid State v	Gravity Cu Sensitivity 20.1 Sensitivi 1 9 1 /V Exci	Manufacturer Model Serial Number Cal Due Date stom Units Excitati Excitati Excitati	Dytran 760083 0438 8/1/2012 Input Di Offset on n Source on Value	viders Enabled Internal 7	Shunt Calibration Shunt Value 100000 Gauge Resistance 350 Manual RCal - Target RCal - Target - 0.0434563 Manual RCal + Target RCal + Target - 0.0434563
	<					
Name Units	Manufacturer Model !	Serial Sensitivity			Offset	
Accel_0189 g	Dytran 7600B3 (438 20.1 mv /1 g			0	
F1 Disconnect	F3 Import Sensors F4 Export Sensors	F5 New Sensor Sensor	F7 Pr	F8 ysical Cal	F9	F10 Manual Command F11 In-Vehicle Display F12 Sensor Help

Continue adding sensors in this manner until you have defined all of the sensors used in the test.

4. Assign Sensors to Channels

The next step is to assign sensors to channels, and configure basic parameters for each sensor in TCS by setting the Gain, Balance type, and Calibration type. This is accomplished in the 'Tags and Channels' screen.

To assign a sensor to a channel, highlight the desired channel in the Channel Tree on the left and then select the sensor from the Sensor drop-down. As each sensor is assigned to a channel, the assignment will appear in the table at the bottom of the window. This table provides a detailed overview of all channel assignments and is for display only; it cannot be used for editing.

M Mars Labs TCS 2.6.4.5 Current Test Device Settings Help	test: Dytran_1	_20120210	DGEG	k	Local Ir	idex: 0000 Free:	217.84 GB	Device Index: 00	DO Free: O bytes
1: Configuration			2: R	untime				3: Export	
A: Device Configuration	1	B: Sensors			C: Tags and Cha	innels		D. Recording Opti	ons
$\begin{tabular}{ c c c c c } \hline \hline$	Name: Accel Sensor: Accel Gain: 16 Bal Type: YES Warning: need t Editing Channel 1	Channel 1 annel Enabled 0189 v o balance.	Cal Type: RCAL Bal Value: 0	>	Eng Units Range Resolution Excitation	g ± 6.368 g 0.00019434 g 7 V			
			NOTE: Grid is F	lead-Only					
Device # Name	SensorName	Gain	BalType	BalValue	CalType	InputDividers	Range	Resolution	Excitation
Pod (Port 1) 1 Accel Chann F1 F2 F3	Acce_0189	16 F5	YES F6	0 F7	F8	ND F9 Get Balance	± 6.368 g F10 Manual	0.00019434 g F11 In-Vehicle	F12

NOTE: In the Tags and Channels screen, all channels are initially assigned to a default voltage sensor type.

Continue assigning sensors to channels until all sensors have been assigned for all of the channels of all connected devices, then select 'SAVE' in the TEST menu to save your test configuration. TCS is now configured for calibration and testing.

CALIBRATION

With the system now configured in TCS, the next step is to perform a Calibration on the sensors. To illustrate the process, we will use an example of a calibration using a Dytran accelerometer.

Background

Due to the design of the calibration circuitry, resistive calibration (RCAL) values in TCS are valid only for an excitation voltage of 2.048V. Since Dytran accelerometers are calibrated using a much higher excitation voltage (7 volts), the RCAL values will have to be determined manually in order to calibrate the sensors. The following example will illustrate the process.

Procedure

Beginning at the Sensors screen, a Dytran accelerometer sensor is configured for a 7 volt excitation as shown below. At this point, however, the displayed *Shunt Calibration* values are not correct for the chosen excitation voltage. We will need to determine what the calibration values are supposed to be and manually enter them.

Mars Labs TCS 2.6.4.5 C	Current test: dac_	2-9-2012				
Test Device Settings Help					Local Index: 0000 Free: 21	7.92 GB Device Index: 0800 Free: 0 KB
1: Config	puration	2: Runtime			3	t Export
A: Device Configuratio	n	B: Sena	ors	C: Tags and Chan	vels	D. Recording Options
Voltage Acceleration	Name:	Accel	Manufact	burer Dytran		
Accel Strain	Description		Covid Nov	Model 7600B3		
- Digital - Thermocouple			Cal Due (Date 8/1/2012		
- Other - Displacement	Eng Units	g v Gravity	Custom Units	Input Dividers Enable	d	
Pressue	Type: Solid State	v Senativly 20.1 1 1	Seruitvity (m/) 9 /V Exck	Offree 0 Excitation Excitation Value Excitation Value 2	Shurt Calibration Shurt Value Gauge Resistance Gauge Gauge Resistance Gauge Gauge	00 34563 24563
Name Units Manuf Accel g Dytran	acturer Model 760083	Senial Sensitivity 0438 20.1 mv / 1 g			Offset 0	
F1 F2	F3 Import Sensors	F4 Export Sensors Rew Ser	Isor F6 Remove Sensor	F7 F8 Physical Cal	F3 F10 Marual Command	F11 In-Vehicle Display

NOTE: For more information on RCAL, see the TCS User Manual

Switching to the Tags and Channels screen, configure the sensor for Cal Type = 'RCAL' and Bal Type = 'Yes'.

Mars Labs TCS 2.6.4.5 Current test: d	ac_2-9-2012					. 0 ×		
Test Device Settings Help			0		Local Index: UUUU Free: 217.91	GB Device Index: UUUU Free: 0 KB		
A: Device Continuation		B: Sensors	C: Tr	igs and Channels	D. Recorded Delate			
Sir DAC - Chan, 01 - Chan, 02 - Chan, 03 - Chan, 04 - Chan, 05 - Chan, 13 - Chan, 15 - Chan, 15 - Chan, 15	Name: Chan,01 Channel Senece Accel Gain: 4 Bal Type: YES Warning: need to bal Edding Channel 1	Enobled Cal Type: RLAL w Bal Value: 0	Eng Units 9 Range 22 Resolution 0.00 Excitation 7V	.472 g 0077736 g				
			NOTE: Grid is Read-	Only				
Device # Name	SensorName G	iain BalType	BalValue CalT	ype InputDiv	viders Range R	esolution Excitation		
F1 Disconset F2 F3	F4	F5 F8	F7	F8 Ge	F3 Balance Marual Carmand	F11 In-Venicle Display		

Now we can check the resistive calibration (RCAL) values for the sensor.

Connect to the Titan device by clicking 'Connect' [F1]. Switch to the Single Pod Monitor screen (under the Runtime tab) and click 'Scan' to begin scanning. Perform a Balance operation by clicking on 'Balance' [F10] and responding YES to the prompt.

Now click on 'Toggle Cal –' [F8]. Record the value that is displayed ("-1.065" in the example below).

Mars Labs TCS 2.6.4.5 Current to	est: dac_2-9-2012						
Test Device Settings Help			Local Index: 0000 Free:	217.89 GB Device Index: 0000 Free: 0 bytes			
1: Configuration		2 Runtime		3: Export			
A: Runtime Plot	B: Single Pod Monitor	C: Multiple Pod Monitor	Multiple Plots	Min Max Display			
Detach (Channel Name)) (Value) (Units) (Cal Target)	* Channels with > 2% Relative Error are marked	d red during Cal +/-				
Chan_01	-1.065 9 -0.047343						
Select Pod DAC V							
Exp. Notation Precision 3 \$							
Current File Indices							
Locał							
Remote: 0000							
F1 F2 F3 Disconnect Capture Scar	n F4 Record Locally F5 Record to Device	F6 Clear Graph F7 Toggle Cal +	F8 Toggle Cal · F9 Toggle Cal 0	F11 F12 Ce Save Offsets Un Balance			

1: Configuration 2: Runtime 3: Export A: Flurtime Plot 8: Single Plod Mankor C: Multiple Plod Monkor Multiple Plots Min Max Display Datach (Channel Name) (Value) (Units) (Call Target) * Channels with > 23: Relative Error are motified red during Cal +/- Chan_UT -0.466 o 0.039569		pr 1100				Local Index: UUUU	J Free: 217.89 GB Device Index: UUUU Free
A: Purstine Plot 8: Single Pod Manitor Multiple Pods Min Marc Display Detach (Channel Name) (Value) (Units) (Cal Target) *Channels with > 23; Relative Ence are marked red during Cal +/- Chan_U1 -0.466 o 0.039569		1: Configuration			2. Runtime		3: Export
Detach (Channel Name) (Value) (Units) (Cal Target) *Channels with > 22 Relative Error are moded red during Cal +A Chan_U1 -0.466 > 0.039569 Hext Pod AC Ebp. Notation escion >	A: Runtime	Plot	B: Single Pod Monitor	C: Mu	hiple Pod Monitor	Multiple Plots	Min Max Display
Chan_UT -0.466 a 0.039569 dect Pod. AC v I Exp. Notation existent ©	Detach	(Channel Name)	(Value) (Units) (Cal Ta	rget) * Channels with :	> 2% Relative Error are marked re-	d during Cal +/-	
ter Pod AC		Chan_01	-0.466 9 0.4	039569			
AC 💌	lect Pod						
Exp. Notation scillatri ©	AC Y						
Cision Cision	Eve Natation						
	ecision:						
ent Fie Indices							
al	ent File Indices						
notes 0000	ent File Indices al						

Click on 'Toggle Cal +' [F7]. Record the value that is displayed ("-0.466" in the example below).

Stop the scan by clicking on [F3], and then switch back to the Sensors screen. In the Shunt Calibration pane, enable the checkboxes for Manual entry and then enter the recorded CAL+ and CAL- values into the appropriate 'RCal+ Target' and 'RCal- Target' fields:

Mars Labs TCS 2.6.4.5 Cu	rrent test: dac	_2-9-2012				t and to days. O	000 5 013 00 67	Device Jodew - O	
1: Configu	ration			2 Buntime		Local Index: U	3 Expor	f newice tudes: In	UUU Free: U bytes
A: Device Configuration			B: Sensors		C: Tags and Chann	els	D. R	ecording Options	
Voltage Acceleration Accel Strain	Name: Description	Accel		Manufacturer Model	Dytran 760083				
- Digital				Cal Due Date	8/1/2012	-			
- Other - Displacement	Eng Units	g 🗸 Gr	svity 🗌 C	ustom Units	Input Dividers Enables				
- Pressure	Type: Solid State		enzibvly 10.1 Senzih 1 g 1 /V Exc	nily (mv) Excite eit	Offree 0 ation from Source Internal ation Value 7	Shurt Calk Shur Gauge Resi V Manua RCal- V Manua RCal-	ration t Value 100000 stance 350 RCol - Target Target 1.065 RCol + Target - Target - 466		
Name Units Manufac	Sturer Model 760083	Serial Ser 0438 20	nahivity 1 mo∕1 g			Officet 0			
F1 F2	F3 Import Sensors	F4 Export Sensors	New Sensor Rem	P6 love Sensor	F7 F8 Physical Cal	F9	F10 Manual Command	F11 In-Vehicle Display	F12 Sensor Help

To check the calibration, return to the Single Pod Monitor screen and begin scanning. With the sensor oriented right-side up, observe a value of ~1g:

🐠 Mars Labs TCS 2.6.4.5 Curren	t test: dac_2-9-2012							- • ×
Test Device Settings Help					Local Index: 000	0 Free: 217.09 GB	Device Index: 00	00 Free: 0 bytes
1: Configuration		2. Buntime			3: Export			
A: Runtime Plot	B: Single Pod Monitor	C: M	ultiple Pod Monitor		Multiple Plots		Min Max Displa	y J
Detach (Chonnel Nor Char_01	ne) (Value) (Units) (Cal To 1.012 a	arget) "Channels wit	h > 2% Relative Error are mar	fked red during Cal +/-				
Select Pod: DAC								
Exp. Notation Precision 3								
Current File Indices Local								
Remote: 0000								
F1 Disconnect F2 Capture S	F3 F4 Record Locally	F5 F6 Record to Devrice F6 Clear Gra	ph F7 Toggle Cal +	F8 Toggle Cal -	F9 Toggle Cal 0	F10 Balance	F11 Save Offsets	F12 Un-Balance

RUNTIME MODES

TCS offers a number of data display options in the Runtime environment. A few example screens are shown below.

Runtime Plot:

A scrolling data display



Multiple Pod Monitor:

Numerical display of data from multiple Pods



Min/Max Display: Minimum and maximum channel values



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Single Pod Monitor: Numerical display of data from a single Pod

1	Configuration			2 Runtime		3 Expot
A: Runtime Plot		B. Single Pod Monitor		C: Multiple Pod Monitor	Multiple Plots	Min Max Display
Defach	(Channel Na	me) (Value) (Units) ((Cal Target)	* Channels with > 2% Relation	ve Encrare marked red during Cal +	
	Over_01	-1.868	v	Dian_09	-1.869 v	
	Over_02	-1.870	v	Chan_10	-1.869 v	
elect Pod KrivRecorder W	Over_03	-1.868	v	Dian_11	-1.870 v	
	Chan_04	-1.868	v	Over_12	-1.870 v	
Exp. Notation	Own_05	-1.867	v	Chan_13	-1.870 v	
0	Over_06	-1.867	v	Dian_14	-1.870 v	
	Chan_07	-1.868	v	Dvan_15	-1.871 v	
	Over_08	-1.869	v	Over_16	-1.871 V	
nent File Indices cal: emote:						

Multiple Plots:

Individual user-selectable channel displays



X/Y Plot: Two channels plotted against each other



Capture

A 'Capture' function available in the Runtime environment allows you to acquire and display a predefined amount of sensor data from a single channel.

When you press 'Capture' (F2), a dedicated capture window appears. Within the window are fields to select the channel and the amount of data to acquire in seconds.

Each time you press the 'Re-acquire Data' button, TCS will capture and display the data from the selected channel. The example below shows a two-second capture of data from a 'sprung' strain gauge:



The Capture window controls related to the display:

'Show Points' checkbox - Toggles the sample points ON/OFF Average - Displays the average value of all data points in Engineering Units 'Plot FFT' checkbox – Replaces the XY plot with an FFT of the sampled data FFT Window Size - Sets the size of the FFT window Plot Power Spectrum – Replaces the XY plot with a Power Spectrum plot

NOTE: The 'Plot FFT' and 'Plot Power Spectrum' checkboxes operate like radio buttons - only one box can be selected at a time.

The Strain Gauge data displayed as an FFT:

The Strain Gauge data displayed as a Power Spectrum Plot:

NOTE: Right-clicking in the plot window will produce a list of options, including saving or printing the screen for post review of the data.

EXPORT

M	Mars I	Labs TCS	6 2.6.4 Cu	ırrent test: pod_11-	22-2011									×
	Test	Device	Settings Help						Loc	al Index:	0000 Free: 134.16 GB	Device Index:	0000 Free: 0	KB
			1: Configuration				2: Runtin	ne			3: E	xport		
F	Export ar	nd Review	Browse Remote Files											
Ir		Name		Size		SizeString		Crea	ed	T	Mars Labs Bench 0002	tdf: Success		-
	F	Mars_Lab	is_Bench_0002.tdf	16055221		15.31 MB		10/1	9/2011 11:00 AM		Exported 1 files successfu	ully, 0 errors.		
		Mars_Lab	is_Bench_0001.tdf	13377502		12.76 MB		10/1	9/2011 10:04 AM					
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						Please	Select Int	ə(s) iü	эхрон					
]	
														_
	F1		F2 F3	F4	F5		F6	F7	F8	E	9 F10	F11	F12	_
	Connec	ct	Show F	FT Review Data	Export D	Data					Sync Files			

To export recorded data sets, access the exporter function by clicking on the 'Export' tab.

The Export window displays all of the locally recorded files created under the current test name. To view files that were recorded remotely on the connected Titan device, click the 'Browse Remote Files' tab at the top, then click the Browse Device button to view the files stored on the device. Data test files stored in alternate locations can be accessed by clicking the Browse SD button.

To transfer remote files, select the desired files from the list and then click Transfer Files. To view newly transferred files, switch back to the 'Export and Review' tab and select any of the standard viewing options. Note that you may have to change the test selected under the 'View Test' drop down in order to see the transferred files.

NOTES:

1. Test files that are recorded remotely will always have a '-r' appended to the file name:

Sample_Test_0002-r.tdf

2. Test files that are imported from alternate locations will have an '- i' appended to the file name:

Imported_Test_003-i.tdf

Reviewing Data

Any test file can be reviewed prior to export by clicking on the 'Review Data' button (F4). This brings up a separate window that displays two views of the data: a thumbnail display of the entire test file (at the top) and a larger display that offers zoom and pan capability (at the bottom). In either display, you can drag across a portion of the data to get a magnified view of that section. Holding down the CTRL key in a magnified view allows you to pan left or right, or up and down. The 'Show Points' button will toggle the sample points on and off, while the 'Fit X' and 'Fit Y' buttons will fit the data into the respective axis.

When finished reviewing the data, click on the CLOSE box to dismiss the window and return to the Export window.

NOTE: Only one Review window can be open at a time. Attempting to review another test while the Review window is open will result in an error.

Exporting Data Files

Test data can be exported in seven file formats:

- WAV PC sound file format. Permits viewing the data graphically using standard PC sound applications.
- CSV 'Comma Separated Value', a plain text data file with fields separated by commas.
- TSV 'Tab Separated Value', a plain text data file with fields separated by tabs.
- RPCIII Standard data format used in noise and vibration measurement/analysis systems.

MATLAB - Data format compatible with MATLAB

- HDF5 Portable data format for managing very large data collections
- BLOb 'Binary Large Object', DBMS files in a binary format

Use the 'Export Format' drop-down to select the desired file format:

View Test:	Current Test 💌	
Export Format:	WAV WAV CSV TSV RPC III Matlab	Export Options
	HDF5 BLOb	

Several of the file formats offer additional exporting options that are accessed by selecting the 'Export Options' button:

CSV / TSV Options:

- CSV/TSV Opti	ions		
🗹 Include Tim	nestamp		
🗹 Enable Dec	cimation		
Decimate By:	100	*	

Include Timestamp - When checked, the Timestamp will be included with the exported CSV or TSV data. An example is shown below.

		A	В	С	D	E	F	G	Н		J	ŀ
1	1	Time	Chan_01	Chan_02	Chan_03	Chan_04	Chan_05	Chan_06	Chan_07	Chan_08	Chan_09	Cha
1	2	Seconds	v	v	v	V	V	V	v –	v –	v	۱
1	3	0	1.707625	1.487	0.427	1.056	0.839	0.632	0.412	0.212	-0.002	0.0
1	4	0.000244	1.708313	1.488	0.427	1.055	0.84	0.632	0.412	0.211	-0.002	0.0
	5	0.000488	1.7085	1.487	0.427	1.056	0.838	0.632	0.412	0.21	-0.003	0.C
1	6	0.000732	1.709688	1.488	0.428	1.058	0.841	0.633	0.412	0.211	-0.001	0.0
1	7	0.000977	1.711375	1.49	0.429	1.058	0.841	0.634	0.413	0.212	-0.002	0.0
1	8	0.001221	1.712625	1.49	0.428	1.058	0.84	0.633	0.412	0.211	-0.003	0.0
	9	0.001465	1.713813	1.492	0.428	1.059	0.841	0.634	0.412	0.212	-0.002	0.C
	10	0.001709	1.715563	1.494	0.429	1.061	0.842	0.635	0.413	0.213	-0.002	0.0

Exported 'CSV' data file with timestamp (viewed in Microsoft Excel)

An example of an exported 'CSV' file might look like this:

Sample_test_0002.csv

where: 'Sample_test' is the test name '0002' indicates the second recorded dataset (indices) '.csv' is the file format

Enable Decimation - When this is checked, exported data will decimated by the value in the 'Decimate By' field. Valid decimation values are in the range of 1 - 1000. Entries can be made by using the increment/decrement button, or by manually entering a value in this field.

DAC OPERATION

The Titan DAC outputs a voltage based on the input voltage for a given Titan Pod channel. For any Pod/DAC pair, Pod channel 1 corresponds to DAC channel 1, Pod channel 2 corresponds to DAC channel 2, etc.

For any test configuration where a DAC is used, the Device Settings in TCS should be set to 'Low Speed' with a Scan Rate of '1200 Hz'. These settings are automatically established when 'Mini-Recorder + DAC' is selected as the device type in TCS, but they may have to be selected for other device types ('Mini-Recorder' or 'CPU').

Relating DAC Output to a Given Input

When the system is running, the DAC translates the input sensor units (e.g. "g" for accelerometers) to an output voltage. Calculating the output voltage based on the sensor input requires an understanding of the relationship between the full-scale input range and the full-scale output range (+/- 10 Volts). The following example explains this.

Example: A Dytran Accelerometer is set up as shown below. In the Sensitivity pane, observe the Sensitivity figure of 20.2 mV/g

A: Device Configuration	n			2: Buntin	-					
A: Device Configuration					•		×	3: Expo	at	
■ Voltage			B: Sensors		C:	Tags and Channels		D. F	Recording Options	
La dependencia de la companya	Name:	Accel_0109		Manufacturer	Dytran Instrur	ments, Inc.				^
Accel_0189	escription			Mod	el 760083					
- Strain - Digital				Serial Number	0189					
Themocouple	1			Cal Due Date	05/31/2011					
- Other - Displacement	Eng Units	g ∨ Grav	ity 🗌 Cu	istom Units	🗌 Input D	lividers Enabled				
Pressure -	Type: Solid State	× 20	nalivity 12 Sensitivi g /VExci	iy (mv) Exc a.	Offset 0 citation itation Source citation Value	Internal V 7 V	Shunt Calbration Shunt Value Gauge Resistance Manual RCal - Ta RCal - Target	100000 350 arget -0.0432412		2
Name Units Manufacture	er Moo	del Serial	Sensitivity			0	Diffset			
Accel_0189 g Dytran Institu	ments, Inc. 780	083 0189	20.2 m/ / 1 g			a				

In the Tags and Channels screen shown below, this sensor is assigned to Channel 1, "Accel Channel 1". The input Gain is set to 16, which affects the Accelerometer sensitivity. For this Gain value, the highlighted row in the table below shows a series of related properties. Notice the Range value of +/- 6.3364g. This range is the maximum number of g's this channel can have from the accelerometer.

Mars Labs TCS 2.6.4.5 Current	test: Dytran_1_20120210	GEG					- DX
Test Device Settings Help			Local Inc	ex: 0000 Free:	217.84 GB Dev	vice Index: 000	9 Free: 14.28 GB
1: Configuration		2: Runtime			3:	Export	
A: Device Configuration	B: Sensors		C: Tags and Cha	innels		D. Recording Opti	ons
	Name: Accel Channel 1 Channel Enabled Sensor: Accel_0189 Gain: 16	Selling Dou	Eng Units Range	g ± 6.3364 g			
-1_0h_06 -1_0h_07 -1_0h_08 -1_0h_08 -1_0h_08 -1_0h_10	Editor Channel 1	Bal Value:	Resolution	0.00019338 g 7 V			~
Device # Name	SensorName Gain	BalType BalV	alue CalType	InputDividers	Range	Resolution	Excitation
Pod (Port 1) 1 Accel Chann	[Accel_0185] 16	YES 0	HCAL	ND	±53364g	0.00019338 g	7
F1 Disconnect F2 F3	F4 F5	F6	F7 F8	F9 Get Balance Values	F10 Manual Command	F11 In-Vehicle Display	F12

How does this relate to the DAC output voltage?

To convert the reading in 'g' to 'Volts' at the DAC output for this channel, consider that the DAC output can range from -10 Volts to +10 Volts, while the input can accept from -6.3364g to +6.3364g. This gives the relationship:

This says that if the accelerometer is reading 1g, the DAC will have an output of 1.578 Volts. If the accelerometer changes to 2g, the DAC will put out a voltage of 2 X 1.578 Volts = 3.156 Volts.

Delay

There is a small time delay between the input signal (into the Pod) and the output of the DAC. When measuring the time delay, one would see a signal at the input of the Pod, and then when looking at the actual output of that same signal out of the DAC for that channel, the signal will be delayed by a small amount of time (measured in msec). This delay is a function of the TCS Filter Frequency (configured in the 'Device Configuration' tab).

The time delays for different filter settings are shown below. For all filter settings shown, the Scan Rate is always 1200 Hz.

	TCS Filter Frequency	Delay Time (1 / Source HZ) (Calculated)		
И	200	38.9 msec		
1 OC	150	40.3 msec		
12(100	43.1 msec		
te I	80	45.2 msec		
Scan Rai	50	51.5 msec		
	40	55.9 msec		
	20	78.1 msec		

DAC Reconstruction Filter Attenuation

The DAC features a fixed 150 Hz, 3-pole reconstruction filter in the DAC output stage. The filter is enabled or disabled using jumpers on the DAC printed circuit board (configured at the factory). When enabled, the filter will gradually attenuate the DAC output signal as the input frequency is raised.

The table below shows the reconstruction filter characteristic as a percentage of attenuation for specific frequencies. An expanded view of the filter attenuation that occurs at and around the 1% point is shown at right.

Freq	Atten (%)		Freq	Atten (%)
5	0.0%		15	0.5%
10	0.0%		18	0.6%
20	0.9%		20	0.9%
30	2.1%		22	1.1%
40	3.4%		24	1.2%
50	5.5%		26	1.5%
60	7.0%	\backslash	28	1.7%
70	8.1%	\backslash	30	2.1%
80	11.2%		32	2.3%
90	13.5%		34	2.5%
100	16.8%		36	2.9%
110	19.0%		38	3.0%
120	21.0%		40	3.4%
130	23.0%		45	4.1%
140	25.3%		50	5.5%
150	31.3%			

ADDITIONAL RESOURCES

Addition information regarding the equipment covered in this document can be found in the following Titan Device User Manuals:

MNL-1001 – TCS User Manual MNL-1003 – Titan CPU User Manual MNL-1006 – Titan DAC User Manual MNL-1009 – Titan BMS User Manual

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